# An alternative definition for digital convexity 

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# An alternative definition for digital convexity 

Context and objectives

Full convexity

Topological properties

Morphological characterization and algorithm

Planarity, tangency and reversible reconstruction

## Why digital convexity?



- no (infinitesimal) differential geometry for digital shapes
- convexity: a fundamental tool to analyze the geometry of shapes
- identifies convex/concave/flat/saddle regions
- gives locally its piecewise linear geometry
- facets give normal estimations

Natural digital convexity is not satisfactory

Definition (Natural digital convexity (or $H$-convexity)) $X \subset \mathbb{Z}^{d}$ is digitally convex iff $\operatorname{cvxh}(X) \cap \mathbb{Z}^{d}=X$



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Definition (Natural digital convexity (or H-convexity)) $X \subset \mathbb{Z}^{d}$ is digitally convex iff $\operatorname{cvxh}(X) \cap \mathbb{Z}^{d}=X$

$\Rightarrow$ convex !

Digital convexity does not imply digital connectedness !

## Usual digital convexity adds connectedness

Definition (Usual digital convexity)
$X \subset \mathbb{Z}^{d}$ is digitally convex iff $\operatorname{cvxh}(X) \cap \mathbb{Z}^{d}=X$ and $X$ connected

- many more or less equivalent definitions in 2D: straight segment convexity, triangle convexity, ... [Minsky, Papert 88], [Kim, Rosenfeld 83], [Huübler, Klette, Voss89], . . .


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- none extends well to 3D or more



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## Cubical grid, intersection complex

- cubical grid complex $\mathcal{C}^{d}$
- $\mathcal{C}_{0}^{d}$ vertices or 0 -cells $=\mathbb{Z}^{d}$
- $\mathcal{C}_{1}^{d}$ edges or 1 -cells $=$ open unit segment joining 0 -cells
$-\mathcal{C}_{2}^{d}$ faces or 2 -cells $=$ open unit square joining 1 -cells
- intersection complex of $Y \subset \mathbb{R}^{d}$

$$
\overline{\mathcal{C}}_{k}^{d}[Y]:=\left\{c \in \mathcal{C}_{k}^{d}, \bar{c} \cap Y \neq \emptyset\right\}
$$


cells $\overline{\mathcal{C}}_{0}^{d}[Y], \overline{\mathcal{C}}_{1}^{d}[Y], \overline{\mathcal{C}}_{2}^{d}[Y]$

## Full convexity

Definition (Full convexity)
A non empty subset $X \subset \mathbb{Z}^{d}$ is digitally $k$-convex for $0 \leqslant k \leqslant d$ whenever

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\begin{equation*}
\overline{\mathcal{C}}_{k}^{d}[X]=\overline{\mathcal{C}}_{k}^{d}[\operatorname{cvxh}(X)] . \tag{1}
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Subset $X$ is fully convex if it is digitally $k$-convex for all $k, 0 \leqslant k \leqslant d$.

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Subset $X$ is fully convex if it is digitally $k$-convex for all $k, 0 \leqslant k \leqslant d$.

Full convexity eliminates too thin digital convex sets in arbitrary dimension.


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## Context and objectives

## Full convexity

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## Digital connectedness

Theorem
If the digital set $X \subset \mathbb{Z}^{d}$ is fully convex, then $X$ is $d$-connected.
Proof.

- for $x, y \in X$, segment $x-y$ intersects cells $c_{0}, c_{1}, \ldots, c_{m}$,
- each $c_{i}$ touches at least one corner $z_{i} \in X$,
- each $c_{i}$ is a face of $c_{i+1}$ or inversely,
- implies $z_{i}$ and $z_{i+1}$ shares a unit cube, hence $d$-connected

[ $x, y$ ]

intersected cells $c_{i}$

points $z_{i}$


## Simple connectedness

## Theorem

If the digital set $X \subset \mathbb{Z}^{d}$ is fully convex, then the body of its intersection complex is simply connected.
Proof.

- let $\mathcal{A}:=\{x(t), t \in[0,1]\}$ be a closed curve in $\left\|\overline{\mathcal{C}}^{d}[X]\right\|$
- sequence of intersected cells $c_{i} \in \overline{\mathcal{C}}^{d}[X]$
- sequence of associated corners $z_{i} \in X$
- homotopy between $\mathcal{A}$ and path $z_{0}-z_{1}-\cdots-z_{n}-z_{0}$
- path $z_{0}-z_{1}-\cdots-z_{n}-z_{0}$ subset of $\operatorname{cvxh}(X) \Rightarrow$ contractible

$\mathcal{A}$

intersected cells $\left(c_{i}\right)$

path $z_{0}-z_{1}-\cdots-z_{n}-z_{0}$


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## Discrete Minkowski sum $U_{\alpha}$

- let $X \subset \mathbb{Z}^{d}$, denote $\mathrm{e}_{i}(X)$ the translation of $X$ with axis vector $\mathrm{e}_{i}$
- let $I^{d}:=\{1, \ldots, d\}$ be the set of possible directions
- let $U_{\emptyset}(X):=X$, and, for $\alpha \subset I^{d}$ and $i \in \alpha$, recursively $U_{\alpha}(X):=U_{\alpha \backslash i}(X) \cup \mathrm{e}_{\mathrm{i}}\left(U_{\alpha \backslash i}(X)\right)$.

$U_{\emptyset}(X)=X$

$U_{\{2\}}(X)=U_{\emptyset}(X) \cup \mathrm{e}_{2}\left(U_{\emptyset}(X)\right) \quad U_{\{1,2\}}(X)=U_{\{1\}}(X) \cup \mathrm{e}_{1}\left(U_{\{1\}}(X)\right)$


## A morphological characterization

Theorem
$A$ non empty subset $X \subset \mathbb{Z}^{d}$ is digitally $k$-convex for $0 \leqslant k \leqslant d$ iff

$$
\begin{equation*}
\forall \alpha \in I_{k}^{d}, U_{\alpha}(X)=\operatorname{cvxh}\left(U_{\alpha}(X)\right) \cap \mathbb{Z}^{d} . \tag{2}
\end{equation*}
$$

It is thus fully convex if the previous relations holds for all $k, 0 \leqslant k \leqslant d$.

$=$

$\operatorname{cvxh}\left(U_{\{1\}}(X)\right) \cap \mathbb{Z}^{d}$

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$X$

$U_{\{1\}}(X)$

$\operatorname{cvxh}\left(U_{\{1\}}(X)\right) \cap \mathbb{Z}^{d}$

## Algorithm in arbitrary dimension

$U_{\alpha}(X)$ easily computed while convex hull algorithms exist in arbitrary dimension. Slowest part is lattice point enumeration in convex hull.

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## Thick enough arithmetic planes are full convex



Arithmetic plane

- irreducible normal vector $N \in \mathbb{Z}^{d}$
- intercept $\mu \in \mathbb{Z}$
- positive thickness $\omega \in \mathbb{Z}, \omega>0$

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P(\mu, N, \omega):=\left\{x \in \mathbb{Z}^{d}, \mu \leqslant x \cdot N<\mu+\omega\right\}
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Theorem
Arithmetic planes are fully convex for thickness $\omega \geqslant\|N\|_{\infty}$.

## Tangency

## Definition

The digital set $A \subset X \subset \mathbb{Z}^{d}$ is said to be $k$-tangent to $X$ for $0 \leqslant k \leqslant d$ whenever $\overline{\mathcal{C}}_{k}^{d}[\operatorname{cvxh}(A)] \subset \overline{\mathcal{C}}_{k}^{d}[X]$. It is tangent to $X$ if the relation holds for all such $k$. Elements of $A$ are called cotangent.


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not tangent

not tangent

## Tangential cover

In 2D, maximal fully convex tangent subsets form the classical tangential cover of [Feschet, Tougne 99]
Theorem
When $d=2$, if $C$ is a simple 2-connected digital contour (i.e.
8 -connected in Rosenfeld's terminology), then the fully convex subsets of $C$ that are maximal and tangent are the classical maximal naive digital straight segments.


## Tangential cover in 3D ? dD ?

- can we define facets of $X$ as inextensible connected pieces of arithmetic planes standard planes along $X$ ?



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- greedy methods to isolate meaningful ones:
[Klette, Sun, Coeurjolly, Sivignon, Kenmochi, Provot, Debled-Rennesson, Charrier, L., ...]


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Tangency extends to $d \mathrm{D}$ !
Tangent subsets in our sense are indeed tangent to $X$ since their convex hull must lie close to $X$.


## Piecewise linear reversible reconstruction in $d \mathrm{D}$

Let $\operatorname{Del}(X)$ be the Delaunay complex of $X$.
Definition
The tangent Delaunay complex $\operatorname{Del}_{T}(X)$ to $X$ is the complex made of the cells $\tau$ of $\operatorname{Del}(X)$ such that the vertices of $\tau$ are tangent to $X$.

- its boundary is the convex hull when $X$ is fully convex,


## Piecewise linear reversible reconstruction in $d \mathrm{D}$

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Input digital shape $X$


Reconstruction $\operatorname{Del}_{\mathrm{T}}(X)$


Bad simplices of $\operatorname{Del}(X)$

Theorem
The body of $\operatorname{Del}_{T}(X)$ is at Hausdorff $L_{\infty}$-distance 1 to $X . \operatorname{Del}_{T}(X)$ is a reversible polyhedrization, i.e. $\left\|\operatorname{Del}_{\mathrm{T}}(X)\right\| \cap \mathbb{Z}^{d}=X$.

## Conclusion

Pros of full convexity

- natural definition in arbitrary dimension that uses $\mathbb{Z}^{d} \subset \mathcal{C}^{d}$
- guarantees connectedness and simple connectedness
- morphological characterization that allows simple convexity check
- thick enough arithmetic planes are fully convex
- entails a consistent definition of tangency
- simple tight and reversible polyhedrization

Cons of full convexity

- $\left(2^{d}-1\right)$ times slower to check convexity

