

# An equivalence relation between morphological dynamics and persistent homology in $n$ -D

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# Outline

- 1 Motivation
- 2 Mathematical background
- 3 Pairing by dynamics implies pairing by persistence
- 4 Pairing by persistence implies pairing by dynamics
- 5 Difference 1D vs.  $n$ -D
- 6 Conclusion

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# Dynamics vs. persistence

## Domains:

- Dynamics  $\in$  Mathematical Morphology
- Topological persistence  $\in$  Persistent Homology.

## Practical uses:

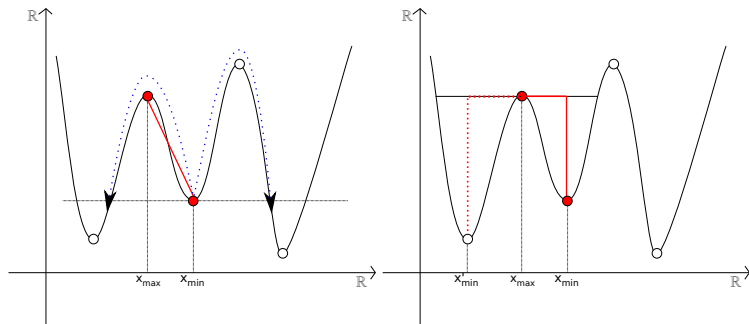
- dynamics  $\rightsquigarrow$  markers  $\rightsquigarrow$  watersheds  $\rightsquigarrow$  segmentation  $\rightsquigarrow$  image analysis,
- persistence  $\rightsquigarrow$  pairings  $\rightsquigarrow$  cancelations  $\rightsquigarrow$  simplification  $\rightsquigarrow$  image visualisation

## Differences:

- dynamics  $\rightsquigarrow$  correspond to regional minima,
- persistence  $\rightsquigarrow$  is related to gradient vector fields (Morse-Smale complexes).

**Both encode topological information of functions.**

## An example



~> same pairings but different definitions!

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# Morse functions

## Morse functions (general definition):

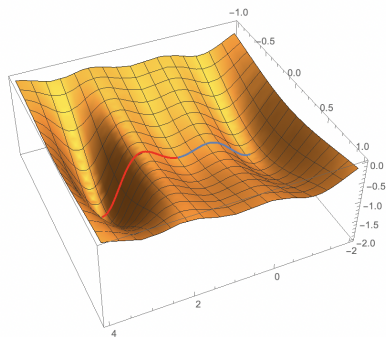
- $f \in C^2(\mathcal{D})$  and the Hessian matrix is not degenerated at the critical points,
- is does not have any plateau,
- for pairings, we need critical values to be unique.

## Dynamics I

- $f : \mathbb{R}^n \rightarrow \mathbb{R}$  a Morse function
- $x_{\min}$  a local minimum of  $f$ ,
- $\gamma$  a path following the graph of  $f$  from  $\gamma(0) := x_{\min}$  to  $\gamma(1)$  s.t.

$$f(\gamma(1)) < f(x_{\min}),$$

- $\text{effort}(\gamma, x_{\min}) = \max_{s \in [0,1]} f(\gamma(s)) - f(x_{\min})$ ,
- $\text{dyn}(x_{\min}) := \min_{\gamma} \text{effort}(\gamma, x_{\min})$ .



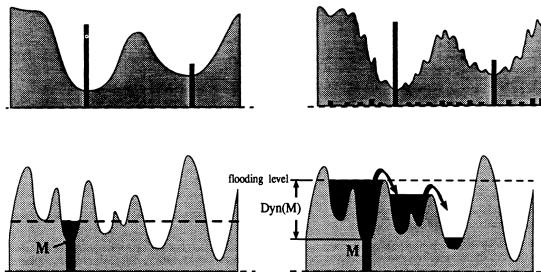
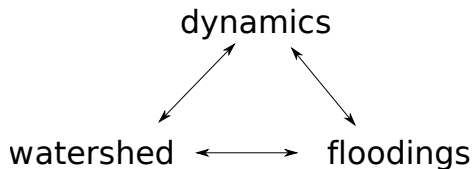
Equivalently,  $\text{dyn}(x_{\min}) = f(x_{1\text{sad}}) - f(x_{\min})$  with  $x_{1\text{sad}}$  the local max of  $f$  corresponding to the minimal effort.

$x_{\min}$  and  $x_{1\text{sad}}$  where the optimal path is at maximum height are then paired by dynamics.



## Dynamics II

An interesting relation in MM:



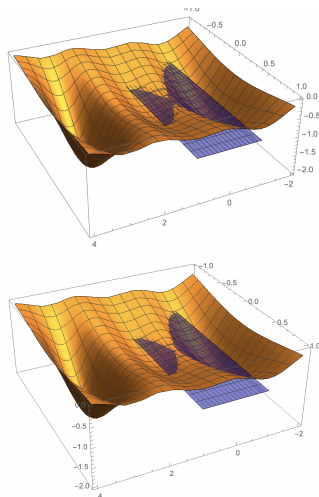
## Topological persistence I

## Pairing by persistence

- $f : \mathbb{R}^n \rightarrow \mathbb{R}$  a Morse function,
- $x_{1\text{sad}}$  a 1-saddle of  $f$ ,
- $C^{1\text{sad}} = CC([f \leq f(x_{1\text{sad}})], x_{1\text{sad}})$ ,
- $CC_1$  and  $CC_2$  the **two** components of  $[f < f(x_{1\text{sad}})]$  whose boundary contains  $x_{1\text{sad}}$ ,
- $\text{rep}_i := \arg \min_{x \in CC_i} f(x)$ ,
- $x_{\min} := \arg \max_{x \in \{\text{rep}_1, \text{rep}_2\}} f(x)$ ,

Then,  $x_{1\text{sad}}$  is paired with  $x_{\min}$  by persistence.

$\Rightarrow$  Topological persistence :=  $f(x_{1\text{sad}}) - f(x_{\min})$ .

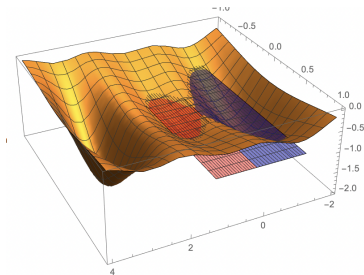


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## Hypothesis

- $f : \mathbb{R}^n \rightarrow \mathbb{R}$  a Morse function,
- $x_{\min}$  a local minimum of  $f$ ,
- $x_{\min}$  paired with  $x_{1\text{sad}}$  by dynamics,
- We define  $C_1 = CC([f < f(x_{1\text{sad}})], x_{\min})$ .
- We define  $C_2$  the component of  $[f < f(x_{1\text{sad}})]$  which does *\*not\** contain  $x_{\min}$  and whose closure contains  $x_{1\text{sad}}$ .



## Property (P1)

$$x_{\min} = \arg \min_{x \in C_1} f(x)$$

## Property (P2)

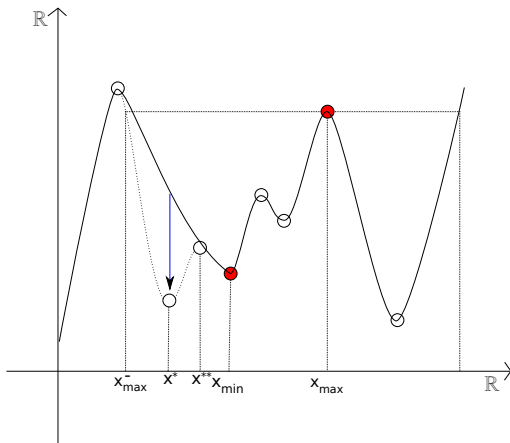
$$x'_{\min} := \arg \min_{x \in C_2} f(x) \text{ satisfies } f(x'_{\min}) < f(x_{\min}).$$

## Theorem

$x_{1\text{sad}}$  is paired with  $x_{\min}$  by persistence.

## Property (P1)

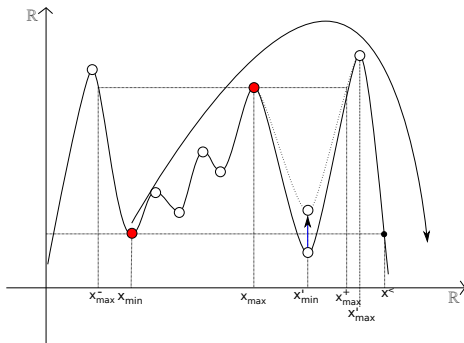
$$x_{\min} = \arg \min_{x \in C_1} f(x)$$



Intuition: if there exists  $x^* \in C_1$  s.t.  $f(x^*)$  is lower than  $f(x_{\min})$ ,  
 $\text{dyn}(x_{\min}) < f(x_{\text{lsad}}) - f(x_{\min}) \rightsquigarrow$  contradiction.

## Property (P2)

$x'_{\min} := \arg \min_{x \in C_2} f(x)$  satisfies  $f(x'_{\min}) < f(x_{\min})$ .



Intuition: if we increase  $f(x'_{\min})$  \*above\*  $f(x_{\min})$ ,  $\text{dyn}(x_{\min})$  increases  $\leadsto$  contradiction.

First main result of this paper:

### Theorem

$x_{\text{lsad}}$  is paired with  $x_{\text{min}}$  by persistence.

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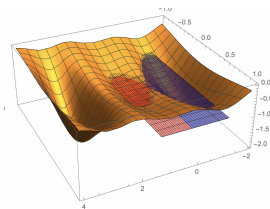
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# Pairing by persistence implies pairing by dynamics I

## Hypothesis

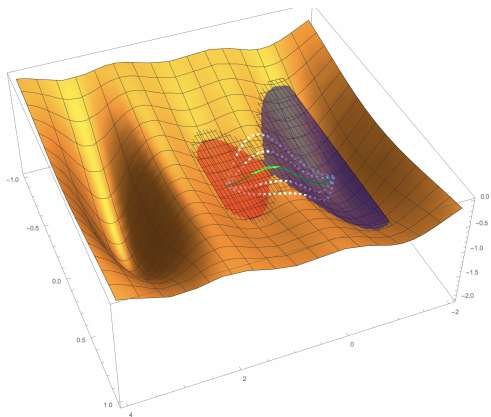
- $f : \mathbb{R}^n \rightarrow \mathbb{R}$  a Morse function with  $x_{1\text{sad}}$  a 1-saddle of  $f$ ,
- $x_{1\text{sad}}$  and  $x_{\text{min}}$  are paired by persistence:
  - $C_1, C_2$  the two components of  $[f < f(x_{1\text{sad}})]$  whose closure contains  $x_{1\text{sad}}$ ,
  - $C_1$  contains  $x_{\text{min}}$  and  $x_{\text{min}} := \arg \min_{x \in C_1} f(x)$
  - $C_2$  does not contain  $x_{\text{min}}$  and  $x'_{\text{min}} := \arg \min_{x \in C_2} f(x)$ ,
  - $f(x'_{\text{min}}) < f(x_{\text{min}})$ .



## Pairing by persistence implies pairing by dynamics II

## Property

- 1  $\exists$  a descending path  $\gamma$  from  $x_{\min}$  to  $x'_{\min}$  corresponding to an effort of  $f(x_{1\text{sad}}) - f(x_{\min})$ ,
- 2 then  $\text{dyn}(x_{\min}) \leq f(x_{1\text{sad}}) - f(x_{\min})$ ,
- 3 to reach a level lower than  $f(x_{\min})$  on  $f$  in an optimal way, the only possibility is to go through a 1-saddle,
- 4 then any optimal descending path goes through  $x_{1\text{sad}}$ ,
- 5 then  $\text{dyn}(x_{\min}) \geq f(x_{1\text{sad}}) - f(x_{\min})$ ,
- 6 then  $\text{dyn}(x_{\min}) = f(x_{1\text{sad}}) - f(x_{\min})$ ,
- 7 the only local extremum satisfying (6) is  $x_{1\text{sad}}$ .



# Pairing by persistence implies pairing by dynamics III

Second main result of this paper:

## Theorem

*When  $f$  is a  $n$ -D Morse function and  $x_{\min}$  and  $x_{1\text{sad}}$  are paired by persistence, then  $x_{1\text{sad}}$  and  $x_{\min}$  are paired by dynamics too.*

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- Not only two directions are possible as in 1D: this number becomes infinite in 2D and beyond,
- We had to prove that at a 1-saddle point (on a Morse function), we have always two components which merge when the threshold sets increase to  $f(x_{1\text{sad}})$ ,
- We had to change systematically the coordinates so that the functions can be written:

$$f(x_1, \dots, x_n) = -x_1^2 + x_2^2 + \dots + x_n^2.$$

- We had to make “algorithmic” the computation of optimal paths in  $n$ -D to prove that they always go through a 1-saddle point,
- the calculus relative to the proofs are a little more complex but the concept is the same.

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## Summary:

- on Morse functions, pairings by persistence and by dynamics are equivalent,
- persistence and dynamics values are then equal,
- another relation between MM and MT:

$$WS(f) \cup WS(-f) = MS(f),$$

- finally, we reinforced the relation between MM and MT!

## Future works:

- extension to discrete Morse functions (Forman),
- investigate if algorithms of MM can be used in PH and conversely,

# Questions

Is this a Morse function?

